



GALGOTIAS UNIVERSITY Programme Structure 2023-24

School/Dept.		DEECE	Program Name				Dr. Teek, IEE		
Semester		II							
S. No.	Course Code	Course Title	L	T	P	S	Credits	Hours	Type
1	E11011220	Engineering Mathematics-I	3	0	0	-	4	5	SEC
2	E11011050	Programming for Problem Solving - I	2	0	1	1	4	5	SEC
3	E201A1200	Basic Electrical & Electronics Engineering	3	0	1	0	4	5	SEC
4	E11011240	Semiconductor and Opto-Electronic Devices	3	0	1	-	4	5	SEC
5	E101010010	Engineering Design and Prototyping	3	0	1	-	4	5	SEC
6	E11011200	Environmental Impact Analysis	2	0	0	0	0	2	VAC
			Total				20		

Semester		III							
S. No.	Course Code	Course Title	L	T	P	S	Credits	Hours	Type
1	E11011290	Chemical and Biological Materials	3	0	0	-	3	3	VAC
2	E11011220	Engineering Mathematics-II	3	0	0	-	4	4	SEC
3	E201A10010	Introduction to Digital Systems	2	0	1	-	3	5	SEC
4	E11012010	OSAP	2	0	1	1	4	5	SEC
5	E11012240	Discrete Mathematics	3	0	0	-	3	3	SEC
6	E101A10400	Communication Skills for Engineers	2	0	1	-	3	4	VAC
7	E11012010	Crags	2	0	0	0	0	2	VAC
			Total				20		

Semester		III							
S. No.	Course Code	Course Title	L	T	P	S	Credits	Hours	Type
1	E11012200	Functions of Complex Variables and Transform	3	0	0	-	3	3	SEC
2	E201A10010	Microcontroller Devices and Systems	3	0	1	1	5	5	SEC
3	E201A0010	Network Analysis and Synthesis	3	0	1	-	4	5	SEC
4	E201A10010	Signals and Systems	3	0	0	-	3	3	SEC
5	E201A10010	Electromagnetic Field Theory	3	0	0	-	3	3	SEC
6	E101A1200	Communication Competency & Aptitude Building-1	1	0	1	-	2	3	VAC
			Total				20		

Semester		IV	Program				Dr. Muhammad		
S. No.	Course Code	Course Title	L	T	P	S	Credits	Hours	Type
1	E11014200	Probability and Stochastic Processes	3	0	0	-	3	3	SEC
2	E201B40010	Control Systems	3	0	0	-	3	3	SEC
3	E201B40010	Physical Machines-I	3	0	1	-	4	5	SEC
4	E201B40010	Fundamentals of Power Systems	3	0	0	-	3	4	SEC
5	E201B40010	Electrical Measurement and Instrumentation	3	0	1	1	5	5	SEC
6	E101A44210	Communication Competency & Aptitude Building-2	1	0	1	-	2	3	VAC
			Total				20		

Semester		V							
S. No.	Course Code	Course Title	L	T	P	S	Credits	Hours	Type
1	E201B50010	Physical Machines-II	3	0	1	-	4	5	SEC
2	E201B50010	Power System Analysis	3	0	0	-	3	3	SEC
3	E201B50010	Power Electronics	3	0	1	1	5	5	SEC
4	E201B50010	Microcontroller and Embedded System	3	0	1	-	4	5	SEC

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web lain hal pada putaran rendah motor listrik bisa menghasilkan torsi besar dan bekerja dengan efisiensi tinggi karena itulah mobil hybrid menggunakan listrik untuk memutar motor listrik yang disimpan di baterai untuk menjalankan pada saat *labsheet praktik mesin listrik staff site universitas* - Feb 10 2022

web torsi pada motor dapat ditentukan dengan rumus umum yaitu $t \times p$ atau $t \times p \times n \times 60$ t torsi motor n m p daya motor w att n jumlah putaran motor rp m terdapat 3 macam daya yaitu daya celah udara p12 daya rotor p2 dan daya keluaran po oleh karena itu torsi pada motor induksi 3 fasa dibedakan menjadi torsi

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web rumus di atas digunakan untuk mencari daya input suatu motor listrik sedangkan daya output motor listrik dapat dicari dengan menggunakan rumus yaitu $p_{out} = 0.1047 \times n \times m \times watt \times 2$ dimana p_{out} daya output motor watt n kecepatan rpm m torsi n m faktor daya cos

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web dan menariknya kita juga dapat memperhitungkan putaran rotor per menit rpm pada sebuah dinamo motor listrik dengan menggunakan rumus berikut ini rpm $f \times 120 / p$ keterangan

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web dalam dunia industri yang menggunakan motor motor listrik umumnya menggunakan motor induksi inverter berfungsi untuk mengatur kecepatan motor tersebut kecepatannya motor induksi ditentukan oleh frekuensi tegangan dan jumlah kutub motor seperti yang dijelaskan dalam rumus menghitung putaran motor atau rpm $n = 120 f / p$ dimana n

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web motor listrik adalah suatu alat yang dapat mengubah energi listrik menjadi tenaga gerak putar dan hal ini tentunya dipengaruhi oleh 3 faktor yaitu daya listrik yang digunakan berapa kecepatannya putaran yang dihasilkan dan berapa besar tenaganya torsi rumus menghitung rpm motor listrik

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semakin sedikit jumlah kutub magnet pole maka putaran motor listrik akan semakin cepat

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web pernyataan ini dapat dibuktikan dengan rumus menghitung rpm dibawah ini $\text{rpm} = f \times 120 / p$ rpm rotation per minute

jumlah putaran dalam satu menit f frekuensi hz p pole jumlah kutub jika sebuah elektro motor memiliki 4 empat kutub

magnet pole dan frekuensi 50hz maka rpm motor listrik tersebut adalah $\text{rpm} = f \times 120 / p$

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dijelaskan dalam rumus menghitung putaran motor atau $\text{rpm} = n / 120 \times f / p$ dimana n jumlah putaran dalam satuan rpm f

frekuensi dalam satuan hz p jumlah kutub jumlah kutub motor telah ditentukan oleh pabrikan saat dibuat

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