$$T = \frac{1}{2}m_1 \dot{\vec{r}}_1^2 + \frac{1}{2}m_2 \dot{\vec{r}}_2^2$$

$$U = U(r) + m_1 g z_1 + m_2 g z_2 \qquad \vec{g} = g\hat{z}$$

$$L = T - U$$

$$L = \frac{1}{2}m_1 \dot{\vec{r}}_1^2 + \frac{1}{2}m_2 \dot{\vec{r}}_2^2 - \left(U(r) + m_1 g z_1 + m_2 g z_2\right)$$

$$\vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{M} \quad , \quad \vec{r} = \vec{r}_1 - \vec{r}_2$$

Express $\vec{r}_1$ and $\vec{r}_2$ in terms of $\vec{R}$ and $\vec{r}$.

$$\vec{R} = \frac{m_1 \vec{r}_1 + m_2(\vec{r}_1 - \vec{r})}{M}$$

$$M\vec{R} = m_1 \vec{r}_1 + m_2 \vec{r}_1 - m_2 \vec{r}$$

$$= \vec{r}_1(m_1 + m_2) - m_2 \vec{r}$$

$$\frac{M\vec{R} + m_2 \vec{r}}{m_1 + m_2} = \vec{r}_1$$

$$\vec{r}_1 = \vec{R} + \frac{m_2}{m_1 + m_2}\vec{r}$$

$\vec{r}_2$: $M\vec{R} = m_1(\vec{r} + \vec{r}_2) + m_2 \vec{r}_2$

$$= m_1 \vec{r} + m_1 \vec{r}_2 + m_2 \vec{r}_2$$

$$\frac{M\vec{R} - m_1 \vec{r}}{m_1 + m_2} = \vec{r}_2$$

$$\vec{r}_2 = \vec{R} - \frac{m_1}{m_1 + m_2}\vec{r} \; ;$$

$$\vec{r}_1 = \vec{R} + \frac{m_2}{m_1 + m_2}\vec{r}$$

$$\vec{r}_2 = \vec{R} - \frac{m_1}{m_1 + m_2}\vec{r}$$

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