

REQUEST FOR ENGINEERING PROPOSAL
BRIDGE REPLACEMENT PROJECT
PLACERVILLE DRIVE BRIDGE AT HANGTOWN CREEK

INTRODUCTION

The City of Placerville is inviting qualified firms to submit proposals to take this project thru the bidding process, including completion of a Preliminary Engineering Feasibility Report phase and perform Project Approval and Environmental Document (PA&ED) services (Task 1), preparation of the complete PS&E (Task 2), and Bidding and Construction Support (Task 3), all leading to the replacement of the Placerville Drive Bridge (State Bridge 25C0029), crossing Hangtown Creek. The Project is located about 0.7 miles west of where Placerville Drive crosses under Hwy. 50, and about 0.3 miles west of the Cold Springs Rd/Home Depot intersection with Placerville Drive, in the City of Placerville. The existing bridge was rated as "Functionally Obsolete" in the Caltrans Bridge Inspection Report dated August 10, 2012. A copy of the report is attached.

The City is looking for a highly qualified firm with complete knowledge of Caltrans Structure Design procedures, the Caltrans Local Assistance Manual and procedures, and the Federal Highway Administration (FHWA) Local Assistance Highway Bridge Program (HBP). The firm must also have substantial experience in California Environmental Quality Act (CEQA) / National Environmental Policy Act (NEPA) environmental review, documentation and permitting procedures. Experience in dealing with replacement of obsolete bridges, public outreach, preparation of environmental documents and bridges structures design is required.

The existing bridge is a narrow two-lane single span Concrete T Beam structure approximately 41 feet long by 28 feet wide. The new bridge is expected to be a simple span box girder or cast-in-place reinforced concrete prestressed slab approximately 85 feet in width, to include 4 lanes, median, shoulder/bike lanes, curbs, gutters, and sidewalks, a modern structure meeting current design standards. This width has been determined by the Placerville Drive Multi-Modal Study completed in 2009, which study is included as an attachment. The Hangtown Creek Comprehensive Watershed Plan, which included completion of a new hydraulic model for Hangtown Creek thru the City of Placerville, was completed in March 2012, and is also included as an attachment. In May 2013 the City received Highway Bridge Program (HBP) funds for a bridge replacement project to begin Preliminary Engineering, and copies of the application/scope definition form (Exhibit 6-A), the special cost approval checklist (Exhibit 6-B), the field review form (Exhibit 7-B), and the request for authorization to proceed with Preliminary Engineering (Exhibit 3-A) are attached.

Quincy Engineering was previously under contract with the City to develop PS&E for a bridge widening project at this location. Preliminary Engineering was originally authorized in 1997. Various challenges arose during the course of that work, including discovery of hazardous waste and cleanup (1999), State budget issues (2001-2003), Red-legged Frog habitat requiring additional studies and consultation with USFWS (2002-2004), accelerated

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Zhe Xu



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Handbook of Scientific Proposal Writing A.Yavuz Oruc,2011-10-25 Investigators their home institutions and funding agencies play significant roles in the development and outcomes of scientific projects Submitting a proposal to a funding agency is only one dimension of a multivariable and complex funding process and understanding this is a good first step toward unlocking the puzzle behind why some research p [Peer Review](#) United States. General Accounting Office,1994

The Electrical Engineer ,1897 *Hispanic Engineer & IT* ,2000-02 Hispanic Engineer Information Technology is a publication devoted to science and technology and to promoting opportunities in those fields for Hispanic Americans

Journal of the American Institute of Electrical Engineers American Institute of Electrical Engineers,1925 Includes preprints of Transactions of the American Institute of Electrical Engineers ISSN 0096 3860 **Practical Control of Electric Machines** Rubén Molina Llorente,2020-03-20 This book presents deep analysis of machine control for different applications focusing on its implementation in embedded systems Necessary peripherals for various microcontroller families are analysed for machine control and software architecture patterns for high quality software development processes in motor control units are described Abundant figures help the reader to understand the theoretical simulation and practical implementation stages of machine control Model based design used as a mathematical and visual approach to construction of complex control algorithms code generation that eliminates hand coding errors and co simulation tools such as Simulink PSIM and finite element analysis are discussed The simulation and verification tools refine and retest the models without having to resort to prototype construction The book shows how a voltage source inverter can be designed with tricks protection elements and space vector modulation Practical Control of Electric Machines Model Based Design and Simulation is based on the author s experience of a wide variety of systems in domestic automotive and industrial environments and most examples have implemented and verified controls The text is ideal for readers looking for an insight into how electric machines play an important role in most real life applications of control Practitioners and students preparing for a career in control design applied in electric machines will benefit from the book s easily understood theoretical approach to complex machine control The book contains mathematics appropriate to various levels of experience from the student to the academic and the experienced professional Advances in Industrial Control reports and encourages the transfer of technology in control engineering The rapid development of control technology has an impact on all areas of the control discipline The series offers an opportunity for researchers to present an extended exposition of new work in all aspects of industrial control **U.S. Government Research & Development Reports** ,1965 [Electro-Mechanical Actuators for the More Electric Aircraft](#) Mirko Mazzoleni,Gianpietro Di Rito,Fabio Previdi,2021-01-19 This book presents recent results on fault diagnosis and condition monitoring of airborne electromechanical actuators illustrating both algorithmic and hardware design solutions to enhance the reliability of onboard more electric aircraft The book begins with an introduction to the current trends in the

development of electrically powered actuation systems for aerospace applications Practical examples are proposed to help present approaches to reliability availability maintainability and safety analysis of airborne equipment The terminology and main strategies for fault diagnosis and condition monitoring are then reviewed The core of the book focuses on the presentation of relevant case studies of fault diagnosis and monitoring design for airborne electromechanical actuators using different techniques The last part of the book is devoted to a summary of lessons learned and practical suggestions for the design of fault diagnosis solutions of complex airborne systems The book is written with the idea of providing practical guidelines on the development of fault diagnosis and monitoring algorithms for airborne electromechanical actuators It will be of interest to practitioners in aerospace mechanical electronic reliability and systems engineering as well as researchers and postgraduates interested in dynamical systems automatic control and safety critical systems

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Optimization of Electric-Vehicle Charging Giulio Ferro, Riccardo Minciardi, Luca Parodi, Michela Robba, 2024-10-01 This book provides models and methods for the optimal management of electrical vehicles through an interdisciplinary approach that brings together knowledge from the sectors of transportation manufacturing and smart grids Optimization of Electric Vehicle Charging explores several optimization models for the scheduling of electric vehicles in a smart grid Both discrete time and discrete event approaches are considered to minimize tardiness charging and production costs on the basis of information like release time due date deadline energy request and availability of energy generated from renewable sources Transportation demand is assessed as well as user equilibrium based approaches for the location of charging stations and for the assignment of users to multiple charging stations Employing illustrations tables and examples to elucidate the ideas presented this book will be of value to researchers and practitioners in the fields of electrical engineering and transportation as well as to graduate and PhD students

Proceedings of the American Institute of Electrical Engineers, 1925 Vols for 1887 1946 include the preprint pages of the institute's Transactions

Electrical Engineering, 1912 *Agricultural Engineering*, 1924 *The Electrical Journal*, 1904 *Proceedings* American Society for Engineering Education, Society for the Promotion of Engineering Education (U.S.), 1927

Proceedings of the ... Annual Meeting Society for the Promotion of Engineering Education (U.S.). Annual Meeting, 1927

Proceedings Society for the Promotion of Engineering Education (U.S.), 1927

Transactions - Manchester Association of Engineers Manchester Association of Engineers, Manchester, Eng, 1902 Includes its Annual report *Biennial Issue for ...* Montana State University--Bozeman, 1974 *Robust Integration of Model-Based Fault Estimation and Fault-Tolerant Control* Jianglin Lan, Ronald J. Patton, 2020-12-11 Robust Integration of Model Based Fault Estimation and Fault Tolerant Control is a systematic examination of methods used to overcome the

inevitable system uncertainties arising when a fault estimation FE function and a fault tolerant controller interact as they are employed together to compensate for system faults and maintain robustly acceptable system performance It covers the important subject of robust integration of FE and FTC with the aim of guaranteeing closed loop stability The reader s understanding of the theory is supported by the extensive use of tutorial examples including some MATLAB based material available from the Springer website and by industrial applications based material The text is structured into three parts Part I examines the basic concepts of FE and FTC providing extensive insight into the importance of and challenges involved in their integration Part II describes five effective strategies for the integration of FE and FTC sequential iterative simultaneous adaptive decoupling and robust decoupling and Part III begins to extend the proposed strategies to nonlinear and large scale systems and covers their application in the fields of renewable energy robotics and networked systems The strategies presented are applicable to a broad range of control problems because in the absence of faults the FE based FTC naturally reverts to conventional observer based control The book is a useful resource for researchers and engineers working in the area of fault tolerant control systems and supplementary material for a graduate or postgraduate level course on fault diagnosis and FTC Advances in Industrial Control reports and encourages the transfer of technology in control engineering The rapid development of control technology has an impact on all areas of the control discipline The series offers an opportunity for researchers to present an extended exposition of new work in all aspects of industrial control **The Engineer** ,1903

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Table of Contents Sample Research Proposal In Electrical Engineering

1. Understanding the eBook Sample Research Proposal In Electrical Engineering
 - The Rise of Digital Reading Sample Research Proposal In Electrical Engineering
 - Advantages of eBooks Over Traditional Books
2. Identifying Sample Research Proposal In Electrical Engineering
 - Exploring Different Genres
 - Considering Fiction vs. Non-Fiction
 - Determining Your Reading Goals
3. Choosing the Right eBook Platform
 - Popular eBook Platforms
 - Features to Look for in an Sample Research Proposal In Electrical Engineering
 - User-Friendly Interface
4. Exploring eBook Recommendations from Sample Research Proposal In Electrical Engineering
 - Personalized Recommendations
 - Sample Research Proposal In Electrical Engineering User Reviews and Ratings
 - Sample Research Proposal In Electrical Engineering and Bestseller Lists
5. Accessing Sample Research Proposal In Electrical Engineering Free and Paid eBooks
 - Sample Research Proposal In Electrical Engineering Public Domain eBooks
 - Sample Research Proposal In Electrical Engineering eBook Subscription Services
 - Sample Research Proposal In Electrical Engineering Budget-Friendly Options
6. Navigating Sample Research Proposal In Electrical Engineering eBook Formats
 - ePub, PDF, MOBI, and More
 - Sample Research Proposal In Electrical Engineering Compatibility with Devices
 - Sample Research Proposal In Electrical Engineering Enhanced eBook Features
7. Enhancing Your Reading Experience
 - Adjustable Fonts and Text Sizes of Sample Research Proposal In Electrical Engineering
 - Highlighting and Note-Taking Sample Research Proposal In Electrical Engineering
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 - Joining Online Reading Communities
 - Participating in Virtual Book Clubs
 - Following Authors and Publishers Sample Research Proposal In Electrical Engineering
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 - Benefits of a Digital Library
 - Creating a Diverse Reading Collection Sample Research Proposal In Electrical Engineering
10. Overcoming Reading Challenges
 - Dealing with Digital Eye Strain
 - Minimizing Distractions
 - Managing Screen Time
11. Cultivating a Reading Routine Sample Research Proposal In Electrical Engineering
 - Setting Reading Goals Sample Research Proposal In Electrical Engineering
 - Carving Out Dedicated Reading Time
12. Sourcing Reliable Information of Sample Research Proposal In Electrical Engineering
 - Fact-Checking eBook Content of Sample Research Proposal In Electrical Engineering
 - Distinguishing Credible Sources
13. Promoting Lifelong Learning
 - Utilizing eBooks for Skill Development
 - Exploring Educational eBooks
14. Embracing eBook Trends
 - Integration of Multimedia Elements
 - Interactive and Gamified eBooks

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