APPLIED NONLINEAR CONTROL

Jean-Jacques E. Slotine
Weiping Li

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Andrea Bacciotti

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Applied Nonlinear Control Jean-Jacques E. Slotine,Weiping Li,1991 Nonlinear systems analysis Phase plane analysis Fundamentals of Lyapunov theory Advanced stability theory Describing function analysis Nonlinear control systems design Feedback linearization Sliding control Adaptive control Control of multi input physical systems **Stabilization and Regulation of Nonlinear Systems** Zhiyong Chen,Jie Huang,2017-04-30 The core of this textbook is a systematic and self contained treatment of the nonlinear stabilization and output regulation problems Its coverage embraces both fundamental concepts and advanced research outcomes and includes many numerical and practical examples Several classes of important uncertain nonlinear systems are discussed The state of the art solution presented uses robust and adaptive control design ideas in an integrated approach which demonstrates connections between global stabilization and global output regulation allowing both to be treated as stabilization problems Stabilization and Regulation of Nonlinear Systems takes advantage of rich new results to give students up to date instruction in the central design problems of nonlinear control problems which are a driving force behind the furtherance of modern control theory and its application The diversity of systems in which stabilization and output regulation become significant concerns in the mathematical formulation of practical control solutions whether in disturbance rejection in flying vehicles or synchronization of Lorenz systems with harmonic systems makes the text relevant to readers from a wide variety of backgrounds Many exercises are provided to facilitate study and solutions are freely available to instructors via a download from springerextras com Striking a balance between rigorous mathematical treatment and engineering practicality Stabilization and Regulation of Nonlinear Systems is an ideal text for graduate students from many engineering and applied mathematical disciplines seeking a contemporary course in nonlinear control Practitioners and academic theorists will also find this book a useful reference on recent thinking in this field *Max-Plus Methods for Nonlinear Control and Estimation* William M. McEneaney,2006-07-25 The central focus of this book is the control of continuous time continuous space nonlinear systems Using new techniques that employ the max plus algebra the author addresses several classes of nonlinear control problems including nonlinear optimal control problems and nonlinear robust H infinity control and estimation problems Several numerical techniques are employed including a max plus eigenvector approach and an approach that avoids the curse of dimensionality The max plus based methods examined in this work belong to an entirely new class of numerical methods for the solution of nonlinear control problems and their associated Hamilton Jacobi Bellman HJB PDEs these methods are not equivalent to either of the more commonly used finite element or characteristic approaches Max Plus Methods for Nonlinear Control and Estimation will be of interest to applied mathematicians engineers and graduate students interested in the control of nonlinear systems through the implementation of recently developed numerical methods *Absolute Stability of Nonlinear Control Systems* Xiaoxin Liao,Pei Yu,2008-07-16 Following the recent developments in the field of absolute stability Prof Xiaoxin Liao in conjunction with Prof Pei Yu has

created a second edition of his seminal work on the subject Liao begins with an introduction to the Lurie problem and Lurie control system before moving on to the simple algebraic sufficient conditions for the absolute stability of autonomous and non autonomous ODE systems as well as several special classes of Lurie type systems The focus of the book then shifts toward the new results and research that have appeared in the decade since the first edition was published This book is aimed to be used by undergraduates in the areas of applied mathematics nonlinear control systems and chaos control and synchronisation but may also be useful as a reference for researchers and engineers The book is self contained though a basic knowledge of calculus linear system and matrix theory and ordinary differential equations is a prerequisite

Nonlinear Control Systems II Alberto Isidori,1999-09-22 This eagerly awaited follow up to Nonlinear Control Systems incorporates recent advances in the design of feedback laws for the purpose of globally stabilizing nonlinear systems via state or output feedback The author is one of the most prominent researchers in the field *Stable Adaptive Control and Estimation for Nonlinear Systems* Jeffrey T. Spooner,Manfredi Maggiore,Raúl Ordóñez,Kevin M. Passino,2004-04-07 Includes a solution manual for problems Provides MATLAB code for examples and solutions Deals with robust systems in both theory and practice Local Stabilizability of Nonlinear Control Systems Andrea Bacciotti,1992 This is one of the first books presenting stabilizability of nonlinear systems in a well organized and detailed way the problem its motivation features and results Control systems defined by ordinary differential equations are dealt with Many worked examples have been included The main focus is on the mathematical aspects of the problem but some important applications are also described This book will be suitable as a textbook for advanced university courses and also as a tool for control theorists and researchers An extensive list of references is included **Analysis and Control of Nonlinear Process Systems** Katalin M. Hangos,József Bokor,Gábor Szederkényi,2006-04-18 This straightforward text makes the complicated but powerful methods of non linear control accessible to process engineers Not only does it cover the necessary mathematics but it consistently refers to the widely known finite dimensional linear time invariant continuous case as a basis for extension to the nonlinear situation

Nonlinear and Optimal Control Systems Thomas L. Vincent,Walter J. Grantham,1997-06-23 Designed for one semester introductory senior or graduate level course the authors provide the student with an introduction of analysis techniques used in the design of nonlinear and optimal feedback control systems There is special emphasis on the fundamental topics of stability controllability and optimality and on the corresponding geometry associated with these topics Each chapter contains several examples and a variety of exercises **Advances and Applications in Nonlinear Control Systems** Sundarapandian Vaidyanathan,Christos Volos,2018-04-25 The book reports on the latest advances and applications of nonlinear control systems It consists of 30 contributed chapters by subject experts who are specialized in the various topics addressed in this book The special chapters have been brought out in the broad areas of nonlinear control systems such as robotics nonlinear circuits power systems memristors underwater vehicles chemical processes observer design output

regulation backstepping control sliding mode control time delayed control variables structure control robust adaptive control fuzzy logic control chaos hyperchaos jerk systems hyperjerk systems chaos control chaos synchronization etc Special importance was given to chapters offering practical solutions modeling and novel control methods for the recent research problems in nonlinear control systems This book will serve as a reference book for graduate students and researchers with a basic knowledge of electrical and control systems engineering The resulting design procedures on the nonlinear control systems are emphasized using MATLAB software **Nonlinear Control in the Year 2000** Alberto Isidori,Francoise Lamnabhi-Lagarrigue,Witold Respondek,2000-11-17 Control of nonlinear systems one of the most active research areas in control theory has always been a domain of natural convergence of research interests in applied mathematics and control engineering The theory has developed from the early phase of its history when the basic tool was essentially only the Lyapunov second method to the present day where the mathematics ranges from differential geometry calculus of variations ordinary and partial differential equations functional analysis abstract algebra and stochastic processes while the applications to advanced engineering design span a wide variety of topics which include nonlinear controllability and observability optimal control state estimation stability and stabilization feedback equivalence motion planning noninteracting control disturbance attenuation asymptotic tracking The reader will find in the book methods and results which cover a wide variety of problems starting from pure mathematics like recent fundamental results on non analycity of small balls and the distance function through its applications to all just mentioned topics of nonlinear control up to industrial applications of nonlinear control algorithms Nonlinear Control and Filtering Using Differential Flatness Approaches Gerasimos G. Rigatos,2015-06-25 This monograph presents recent advances in differential flatness theory and analyzes its use for nonlinear control and estimation It shows how differential flatness theory can provide solutions to complicated control problems such as those appearing in highly nonlinear multivariable systems and distributed parameter systems Furthermore it shows that differential flatness theory makes it possible to perform filtering and state estimation for a wide class of nonlinear dynamical systems and provides several descriptive test cases The book focuses on the design of nonlinear adaptive controllers and nonlinear filters using exact linearization based on differential flatness theory The adaptive controllers obtained can be applied to a wide class of nonlinear systems with unknown dynamics and assure reliable functioning of the control loop under uncertainty and varying operating conditions The filters obtained outperform other nonlinear filters in terms of accuracy of estimation and computation speed The book presents a series of application examples to confirm the efficiency of the proposed nonlinear filtering and adaptive control schemes for various electromechanical systems These include industrial robots mobile robots and autonomous vehicles electric power generation electric motors and actuators power electronics internal combustion engines distributed parameter systems and communication systems Differential Flatness Approaches to Nonlinear Control and Filtering will be a useful reference for

academic researchers studying advanced problems in nonlinear control and nonlinear dynamics and for engineers working on control applications in electromechanical systems **Towards Constructive Nonlinear Control Systems Analysis and Design** Mario Sassano,David Angeli,Alessandro Astolfi,2012 This work presents a novel method to solve analysis and design problems for nonlinear control systems the classical solutions of which rely on the solvability or on the solution itself of partial differential equations or inequalities The first part of the thesis is dedicated to the analysis of nonlinear systems The notion of Dynamic Lyapunov function is introduced These functions allow to study stability properties of equilibrium points similarly to standard Lyapunov functions In the former however a positive definite function is combined with a dynamical system that render Dynamic Lyapunov functions easier to construct than Lyapunov functions These ideas are then extended to characterize Dynamic Controllability and Observability functions which are exploited in the model reduction problem for nonlinear systems Constructive solutions to the L2 disturbance attenuation and the optimal control problems are proposed in the second part of the thesis The key aspect of these solutions is the definition of Dynamic Value functions that generalizing Dynamic Lyapunov functions consist of a dynamical feedback and a positive definite function In the last part of the thesis a similar approach is utilized to simplify the observer design problem via the Immersion and Invariance technique Finally the effectiveness of the methodologies is illustrated by means of several applications including range estimation and the optimal robust control of mechanical systems combustion engine test benches and the air path of a diesel engine

Nonlinear Control Systems Alberto Isidori,1995-08-11 The purpose of this book is to present a self contained description of the fun damentals of the theory of nonlinear control systems with special emphasis on the differential geometric approach The book is intended as a graduate text as weil as a reference to scientists and engineers involved in the analysis and design of feedback systems The first version of this book was written in 1983 while I was teach ing at the Department of Systems Science and Mathematics at Washington University in St Louis This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana Champaign in 1987 at the Carl Cranz Gesellschaft in Oberpfaffenhofen in 1987 at the University of California in Berkeley in 1988 In addition to a major rearrangement of the last two Chapters of the first version this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985 *Sequential Solutions in Nonlinear Control Theory* Buck F. Brown,1964 *Nonlinear Control Systems* Zoran Vukic,2003-02-04 This text emphasizes classical methods and presents essential analytical tools and strategies for the construction and development of improved design methods in nonlinear control It offers engineering procedures for the frequency domain as well as solved examples for clear understanding of control applications in the industrial electrical process manufacturing and automotive industries The authors discuss Properties of nonlinear systems stability linearization methods operating modes and dynamic analysis methods phase trajectories in dynamic analysis of nonlinear systems and harmonic linearization in dynamic analysis of

nonlinear control systems operating in stabilization mode   Constructive Nonlinear Control R. Sepulchre,M. Jankovic,P.V. Kokotovic,2012-12-06 Constructive Nonlinear Control presents a broad repertoire of constructive nonlinear designs not available in other works by widening the class of systems and design tools Several streams of nonlinear control theory are merged and directed towards a constructive solution of the feedback stabilization problem Analysis geometric and asymptotic concepts are assembled as design tools for a wide variety of nonlinear phenomena and structures Geometry serves as a guide for the construction of design procedures whilst analysis provides the robustness which geometry lacks New recursive designs remove earlier restrictions on feedback passivation Recursive Lyapunov designs for feedback feedforward and interlaced structures result in feedback systems with optimality properties and stability margins The design oriented approach will make this work a valuable tool for all those who have an interest in control theory   *Nonlinear Industrial Control Systems* Michael J. Grimble,Paweł Majecki,2020-05-19 Nonlinear Industrial Control Systems presents a range of mostly optimisation based methods for severely nonlinear systems it discusses feedforward and feedback control and tracking control systems design The plant models and design algorithms are provided in a MATLAB toolbox that enable both academic examples and industrial application studies to be repeated and evaluated taking into account practical application and implementation problems The text makes nonlinear control theory accessible to readers having only a background in linear systems and concentrates on real applications of nonlinear control It covers different ways of modelling nonlinear systems including state space polynomial based linear parameter varying state dependent and hybrid design techniques for nonlinear optimal control including generalised minimum variance model predictive control quadratic Gaussian factorised and H design methods design philosophies that are suitable for aerospace automotive marine process control energy systems robotics servo systems and manufacturing steps in design procedures that are illustrated in design studies to define cost functions and cope with problems such as disturbance rejection uncertainties and integral wind up and baseline non optimal control techniques such as nonlinear Smith predictors feedback linearization sliding mode control and nonlinear PID Nonlinear Industrial Control Systems is valuable to engineers in industry dealing with actual nonlinear systems It provides students with a comprehensive range of techniques and examples for solving real nonlinear control design problems   Applied nonlinear control : possibilities and limitations Thomas Vesterholm,1995   **Nonlinear And Adaptive Control: Tools And Algorithms For The User** Alessandro Astolfi,2005-12-15 This book summarizes the main results achieved in a four year European Project on nonlinear and adaptive control The project involves leading researchers from top notch institutions Imperial College London Prof A Astolfi Lund University Prof A Rantzer Supelec Paris Prof R Ortega University of Technology of Compiegne Prof R Lozano Grenoble Polytechnic Prof C Canudas de Wit University of Twente Prof A van der Schaft Politecnico of Milan Prof S Bittanti and Polytechnic University of Valencia Prof P Albertos The book also provides an introduction to theoretical advances in nonlinear and adaptive control and an overview of novel applications of advanced

control theory particularly topics on the control of partially known systems under actuated systems and bioreactors a

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