

PHYS 410 Homework # 8

6.1. On a spherical surface, the longitude and latitude lines are orthogonal.



For a small change in position, we have the change in longitude and latitude:

$$ds_{\theta} = R \cdot d\theta, \quad ds_{\phi} = R \sin\theta \cdot d\phi$$

$$\Rightarrow ds = \sqrt{ds_{\theta}^2 + ds_{\phi}^2} = R \cdot d\theta \sqrt{1 + \sin^2\theta \frac{d\phi^2}{d\theta^2}}$$

$$\Rightarrow L = \int_R ds = R \int_{\theta_1}^{\theta_2} \sqrt{1 + \sin^2\theta \frac{d\phi^2}{d\theta^2}} \cdot d\theta$$

6.3



$$L(P, Q) = \sqrt{x_1^2 + y_1^2 + z_1^2} + \sqrt{x_2^2 + y_2^2 + z_2^2}$$

$$\Rightarrow T = L/c$$

According to Fermat's principle, we get:

$$\frac{\delta T}{\delta x} = 0, \quad \frac{\delta T}{\delta y} = 0.$$

$$\frac{\delta T}{\delta z} = 0 \Rightarrow 2 \cdot \left(\frac{1}{\sqrt{x_1^2 + y_1^2 + z_1^2}} + \frac{1}{\sqrt{x_2^2 + y_2^2 + z_2^2}} \right) = 0 \Rightarrow z = 0 \quad (1)$$

$$\frac{\delta T}{\delta x} = 0 \Rightarrow \frac{x_1}{\sqrt{x_1^2 + y_1^2 + z_1^2}} + \frac{x_2}{\sqrt{x_2^2 + y_2^2 + z_2^2}} = 0 \quad (2)$$



According to (1), when $z=0$, we get from (2):

$$\sin\theta_1 = \sin\theta_2$$

$$\Rightarrow \theta_1 = \theta_2$$

6.5



According to General Geometric relation, we know $\angle APB = \frac{\theta}{2}$.

$$\text{And } \alpha = \frac{\theta - \theta}{2}$$

$$\Rightarrow AP = AB \cdot \sin(\frac{\theta}{2} - \alpha) = AB \cos \frac{\theta}{2} = AB \sin \frac{\theta}{2} = 2R \sin \frac{\theta}{2}$$

$$BP = AB \cdot \sin \alpha = 2R \cdot \cos \frac{\theta}{2}$$

$$\Rightarrow APB = 2R \cdot (\sin \frac{\theta}{2} + \cos \frac{\theta}{2}) = 2\sqrt{2} \sin(\frac{\theta}{2} + \frac{\pi}{4}) R$$

$$\Rightarrow (APB)_{max} = 2\sqrt{2} R \text{ when } \theta = \frac{\pi}{2}, \text{ which is the real path.}$$

6.7

(2.4.2)



In cylinder coordinates, when R is const, the infinitesimal change in position corresponds to

$$ds = \sqrt{R^2 d\phi^2 + dz^2} = dz \sqrt{1 + R^2 \frac{d\phi^2}{dz^2}} = f(\phi, z) dz$$

$$\Rightarrow L = \int_R ds = \int_{\phi_1}^{\phi_2} f(\phi, z) dz$$

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seeking a refresh of the material The book is structured in ten chapters starting with Newton's laws motion with air resistance conservation laws oscillations and the Lagrangian and Hamiltonian Formalisms The last two chapters introduce some ideas in nonlinear dynamics chaos and special relativity Each chapter starts with a brief theoretical outline and continues with problems and detailed solutions A concise presentation of differential equations can be found in the appendix A variety of problems are presented from the standard classical mechanics problems to context rich problems and more challenging problems Key features Presents a theoretical outline for each chapter Motivates the students with standard mechanics problems with step by step explanations Challenges the students with more complex problems with detailed solutions

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work in all cultures as well as they do in Western literate societies *Proceedings of the Royal Society of London* Royal Society (Great Britain),1926 *Essential Classical Mechanics* Choonkyu Lee,Hyunsoo Min,2018-04-17 The authors deliver a highly readable text which should assure a continued supply of practitioners of classical mechanics and its applications Contemporary Physics This is a book on intermediate classical mechanics In this book classical mechanics is presented as a useful tool to analyze the physical universe and also as the base on which the whole pyramid of modern physics has been erected Various mechanical concepts are developed in a highly logical manner with relatively thorough treatments on mathematical procedures and many physically interesting applications Connections to more modern theoretical developments including statistical physics relativity and quantum mechanics are emphasized Classical Mechanics, Volume 2 K Likharev,2018-04-30 *Solutions of Weekly Problem Papers* John James Milne,1885 **Weekly problem papers, with notes. [With] Solutions** John James Milne,1885

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