④ Adjoint and Inverse of Matrix:

→ for a square matrix, adjoint ; $\boxed{adj(A) = (\text{Co-factor matrix})^T}$

→ for a 2×2 matrix:

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \rightarrow Adj(A) = \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix}$$

(sign change)

→ for n×n matrix A:

$$\boxed{|adj\ A|_{n\times n} = |A|^{n-1}} \rightarrow \boxed{|adj \cdot adj \cdot adj \cdots \text{so on } A| = |A|^{(n-1)^2}}$$

Short cut for 3×3 matrix

(Row (R), Middle (M), Last (L))

$$A = \begin{bmatrix} -1 & 3 & -3 \\ 1 & 2 & -2 \\ 2 & 4 & 3 \end{bmatrix}$$

M L T M

1 4 −2 1 / −2 3 −3 −2 / 1 2 −1 1 / 1 4 −2 1

$$\rightarrow adj\ A = \begin{bmatrix} 11 & -6 & 7 \\ -7 & 3 & -5 \\ 2 & 0 & 1 \end{bmatrix}$$

• Inverse- $\boxed{A^{-1} = \frac{1}{|A|} \cdot adj(A)}$ → $\boxed{A \cdot adj(A) = |A| \cdot I}$ → Inverse is defined only for non-singular matrix.

→ $\boxed{|A^{-1}| = \frac{1}{|A|}}$ → $\boxed{(ABC)^{-1} = C^{-1} \cdot B^{-1} \cdot A^{-1}}$

⑤ Types of Square Matrices:

→ Diagonal matrix ; $a_{ij} = \begin{cases} \text{any value} & ; i=j \\ 0 & ; i \neq j \end{cases}$

→ Scalar matrix; $a_{ij} = \begin{cases} k & ; i=j \\ 0 & ; i \neq j \end{cases}$

→ Unit matrix ; $a_{ij} = \begin{cases} 1 & ; i=j \\ 0 & ; i \neq j \end{cases}$

→ Null matrix : All elements zero.

→ Upper triangular matrix $\begin{bmatrix} a & b \\ 0 & c \end{bmatrix}$ → Lower triangular matrix $\begin{bmatrix} a & 0 \\ b & c \end{bmatrix}$

★ For all the above matrices ; $|A|$ = Product of leading diagonal elements.

→ Symmetric matrix : $[A^T = A]$ → Skew-symmetric matrix : $[A^T = -A]$

→ orthogonal matrix :

Main definition: $[A^T = A^{-1}]$

$A \cdot A^T = A A^{-1}$

$A \cdot A^T = I$

$|A \cdot A^T| = |I|$

$\Rightarrow |A| \cdot |A^T| = |I|$

$\Rightarrow |A|^2 = 1$

$\Rightarrow |A| = \pm 1$

★ If A orthogonal $\rightarrow |A| = \pm 1$

★ If $|A| = \pm 1$ ⇏ A is orthogonal.

→ Hermetion Matrix:

→ Complex square matrix if conjugated transpose is equal to matrix.

$$(\bar{A})^T = A.$$

→ for hermitian matrix ; diagonal elements are real (including zero) and upper, lower diagonal elements are conjugate pairs.

Eg→ $A = \begin{bmatrix} 1 & 2-i \\ 2+i & 3 \end{bmatrix} \Rightarrow (\bar{A})^T = \begin{bmatrix} 1 & 2-i \\ 2+i & 3 \end{bmatrix}$

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from functional anal ysis and the theory of operators Although the book focuses on certain mathematical fundamentals it is written from an applications perspective for engineers and applied scientists working in this area Part I is intended to be a somewhat self contained introduction to op erator theory and functional analysis especially those elements necessary for application to problems in electromagnetics The goal of Part I is to ex plain and synthesize these topics in a logical manner Examples principally geared toward electromagnetics are provided With the exception of Chapter 1 which serves as a review of basic electromagnetic theory Part I presents definitions and theorems along with associated discussion and examples This style was chosen because it allows one to readily identify the main concepts in a particular section A proof is provided for all theorems whose proof is simple and straightforward A proof is also provided for theorems that require a slightly more elaborate proof yet one that is especially enlightening being either constructive or illustrative Generally theorems are stated but not proved in cases where either the proof is too involved or the details of the proof would take one too far afield of the topic at hand such as requiring additional lemmas that are not clearly useful in applications A textbook of Engineering Mathematics Part 2 Prof (Dr) Basant Kumar Singh,Dr Sushil Kumar jamariar,Dr Dinesh Singh,2025-03-31 Master the fundamental concepts of Ordinary Differential Equations Partial Differential Equations Fourier Series Complex Variables and Vector Calculus with this well structured and student friendly textbook Designed specifically for B Tech first year students this book provides clear explanations step by step derivations and practical applications to strengthen mathematical problem solving skills Key Features Detailed Coverage Covers essential topics like Second Order Linear Differential Equations Legendre Polynomials Fourier Transforms and Residue Theorem Conceptual Clarity Simplifies complex mathematical concepts with easy to follow explanations and examples Real World Applications Demonstrates the practical relevance of mathematical theories in engineering Problem Solving Approach Includes previous years exam questions to help students prepare effectively Comprehensive Exercises Offers a variety of solved and unsolved problems for practice Perfect for engineering students competitive exam aspirants and mathematics enthusiasts this book serves as an essential resource for mastering the mathematical foundations required for technical studies Enhance your mathematical proficiency and excel in your exams with this indispensable guide Advanced Engineering Mathematics Peter V. O'Neil,1987 Through four editions Peter O Neil has made rigorous engineering mathematics topics accessible to thousands of students by emphasizing visuals numerous examples and interesting mathematical models ADVANCED ENGINEERING MATHEMATICS featuries a greater number of examples and problems and is fine tuned throughout to improve the clear flow of ideas The computer plays a more prominent role than ever in generating computer graphics used to display concepts And problem sets incorporate the use of such leading software packages as MAPLE Computational assistance exercises and projects have been included to encourage students to make use of these computational tools The content is organized into eight parts and covers a wide spectrum of topics including Ordinary Differential Equations Vectors and Linear Algebra Systems of Differential Equations Vector

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