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web based on the user commands the robot moves and pick and place the objects the robotic arm used here is similar to a human arm which is programmed to perform the pick and place functions the remainder of this paper is organized as follows the section 2 provides information about the existing works section 3 gives details of the proposed

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jig boring machine works on the principle of feed in the vertical axis of the hole and its radius in this process rotating tool is moved over the process is given with respect to static work this principle is used for large see more

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web 1 boring and turning have abrasive counterparts in internal and external cylindrical grinding each process is chosen based on the requirements and parameter values of a

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web for a normal boring operation on a lathe the work revolves mounted in the chuck or on the faceplate and the single point boring tool is set to cut and feed for the corresponding

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